11-2-2019

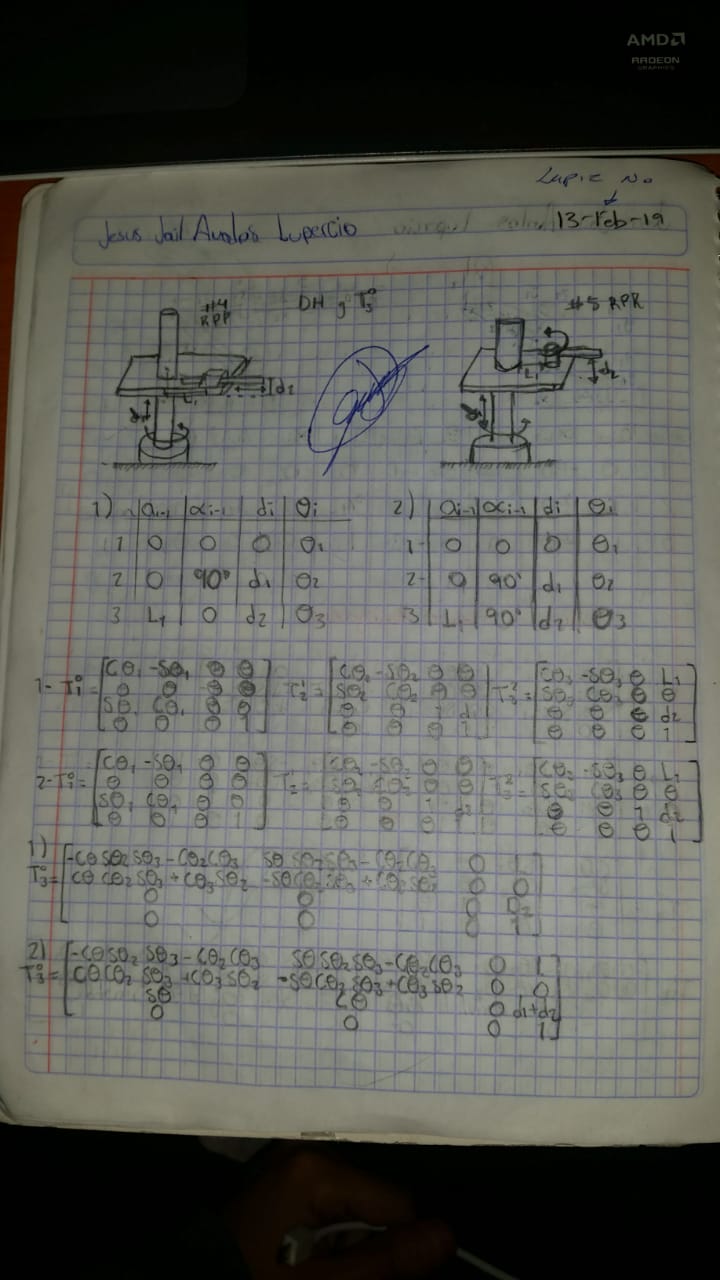
UPZMG

Parámetros DH y TH

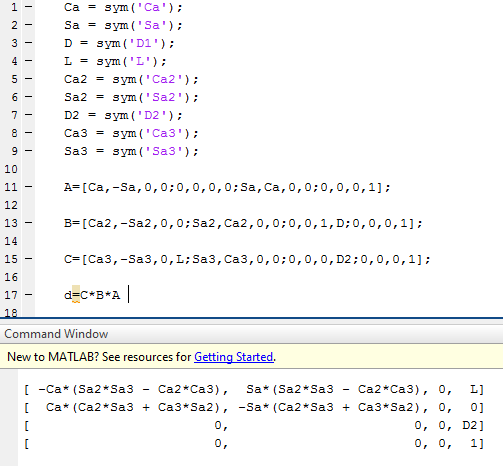
Cinemática de Robots

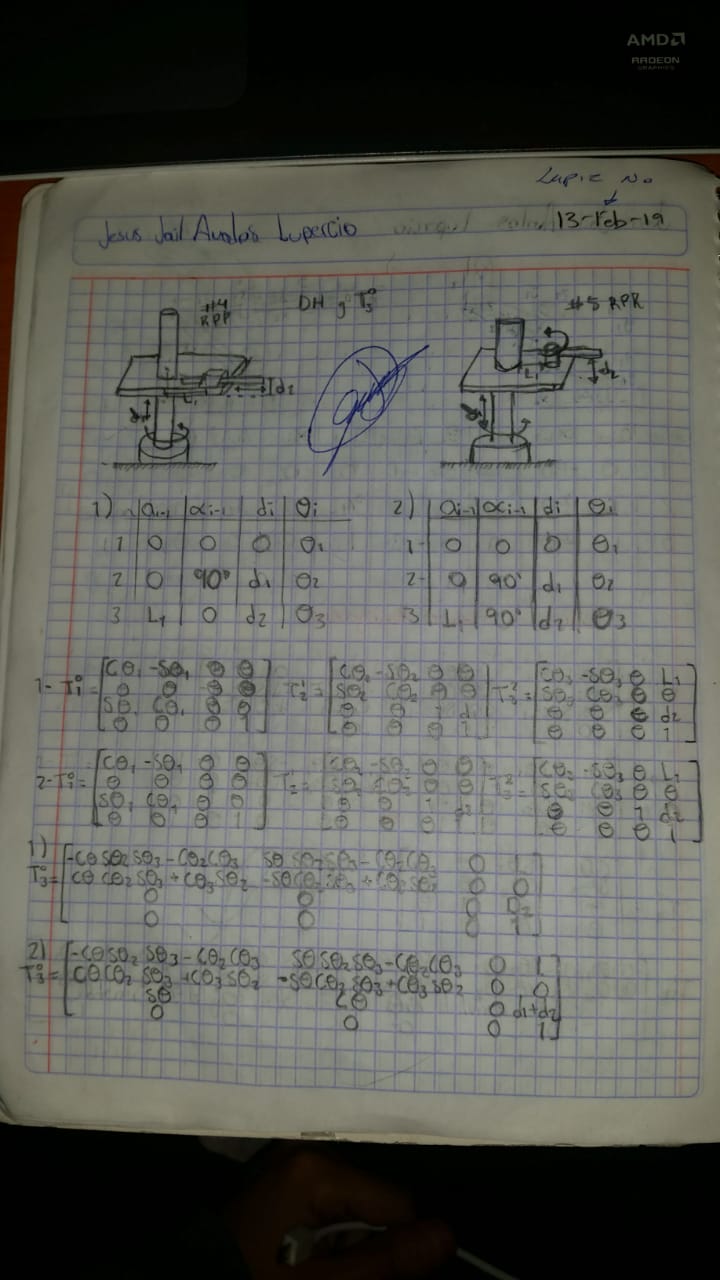
Jesús Jail Avalos Lupercio.

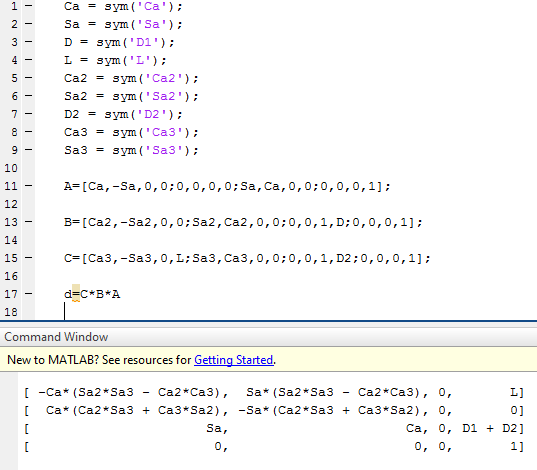
Ing. Mecatrónica 8º A



|  |  |  |  |  |
| --- | --- | --- | --- | --- |
| Eslabón |  |  | d |  |
| 1 | 0 | 0 | 0 |  |
| 2 | 0 | 90º |  |  |
| 3 |  | 0 |  |  |







|  |  |  |  |  |
| --- | --- | --- | --- | --- |
| Eslabón |  |  | d |  |
| 1 | 0 | 0 | 0 |  |
| 2 | 0 | 90º |  |  |
| 3 |  | 90º |  |  |